EXPO Transfer Inquiry Details

Application No 10676155

Art Unit 2863   **Class** 702   **Subclass** 094000

○ **Classification**
◉ **Transfer to GAU**

Request by	LE, JOHN H (#78032)
Gau*	[_____]
Class	[_____] use three digits for class
Subclass	[_____]
Reason	[_____]
Concurred by	[_____] (Examiner No.)

[Add Transfer Inquiry]   [Re-Print Transfer Inquiry]

Transfer History

Transfer Inquiry	From GAU	To GAU	To Class	To Subclass	Requested By Decision By	Concurred By	Date	Reason	Status
		2863	702	094000	Docketed /		9/15/2004		
		2863	702	094000	Docketed /		7/9/2004		
Transfer to 2857	2613	2857	702	104	LEE, RICHARD J / 71286		5/22/2004	image sensor calibration system	C

L Number	Hits	Search Text	DB	Time stamp
-	1	10/676155	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 16:31
-	3	((image with sens$3) same calibrat$4 same (data parameter)) and (alignment same (image with sens$3) same (geometric with axis) same vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 11:41
-	3	((image with sens$3) same calibrat$4 same (data parameter)) and (alignment same (image with sens$3)) and ((geometric with axis) same vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 13:50
-	1	(((image with sens$3) same calibrat$4 same (data parameter)) and (alignment same (image with sens$3))) and ((geometric with travel) same vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 12:24
-	6	(((image with sens$3) same calibrat$4 same (data parameter)) and (alignment same (image with sens$3))) and (geometric same vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 13:00
-	59	702/$.ccls. and ((image with sens$3) same calibrat$4 same (data parameter))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 13:38
-	6	(702/$.ccls. and ((image with sens$3) same calibrat$4 same (data parameter))) and (alignment same (image with sens$3))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 09:47
-	20	(702/$.ccls. and ((image with sens$3) same calibrat$4 same (data parameter))) and (adjust$6 same (image with sens$3))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 13:49
-	5	((702/$.ccls. and ((image with sens$3) same calibrat$4 same (data parameter))) and (adjust$6 same (image with sens$3))) and geometric and vehicle	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 19:11
-	2	EP-1120746-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 15:40
-	4	702/$.ccls. and ((image with sens$3) same calibrat$4 same (data parameter)) and (adjust$6 with image with sens$3) and vehicle	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 13:46
-	10	(image with sens$3) same calibrat$4 same (data parameter) and (adjust$6 with image with sens$3) and vehicle	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 14:39

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-		3	((image with sens$3) same calibrat$4 same (data parameter) and (adjust$6 with image with sens$3) and vehicle) and geometric$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 14:35
-		1	((adjust$6 align$6) with image with sens$3) same (geometric$6 with travel with vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 14:41
-		5	((adjust$6 align$6) with image with sens$3) same (geometric$6 with vehicle)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 15:40
-		1	((adjust$6 align$6) with image with sens$3) and (geometric$6 with vehicle with (travel$6 or mov$6))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 18:26
-		58	((adjust$6 align$6) with position with image with sens$3) and (vehicle with (travel$6 or mov$6))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 15:51
-		3	(((adjust$6 align$6) with position with image with sens$3) and (vehicle with (travel$6 or mov$6))) and ((evalu$6 estimat$6) with image with data)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 15:43
-		15	((adjust$6 align$6) with position with ((image with sens$3) or camera)) and (vehicle with (travel$6 or mov$6)) and ((evalu$6 estimat$6) with image with data)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 20:45
-		2	(geometric$6 adj travel$6 adj axis) and vehicle	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 18:27
-		1	(((geometric$6 with travel$6 with axis) and vehicle) and (image near2 sensor)) and ((align$6 or adjust$6) with position with (image near2 sensor))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 19:00
-		39	(((geometric$6 with travel$6 with axis) and vehicle) and (image near2 sensor)) and ((align$6 or adjust$6) with (image near2 sensor))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 18:31
-		41	((geometric$6 with travel$6 with axis) and vehicle) and (image near2 sensor)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 18:32
-		5	((adjust$6 align$6) with position with ((image with sens$3) or camera)) and (vehicle with (travel$6 or mov$6)) and ((evalu$6 estimat$6) with image with data) and (angle with measur$6)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 18:35

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-		2	((((geometric$6 near2 (travel$6 driv$3) near2 axis) and vehicle) and (image near2 sensor)) and ((align$6 or adjust$6) with position with (image near2 sensor))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 19:01
-		3	((((geometric$6 near2 (travel$6 driv$3) near2 axis) and vehicle) and (image near2 sensor)) and ((align$6 or adjust$6) with (image near2 sensor))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 19:01
-		1	(intrinsic with calibration with data) and (camera with principal with point) and (camera with principal with distance) and (distortion with parameter) and (glass with pane)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 20:49
-		1	(intrinsic with calibration with data) and (camera with principal with point) and (camera with principal with distance) and (glass with pane)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 20:48
-		1	(intrinsic with calibration with data) and (camera with principal with point) and (camera with principal with distance)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 20:48
-		1	(intrinsic with calibration with data) and (camera with point) and (camera with distance) and (distortion with parameter) and (glass with pane)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 20:50
-		1	(intrinsic with calibration with data) and (camera with point) and (camera with distance) and (distortion with parameter) and glass	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/21 20:50
-		11	("4152061" | "4236794" | "4789940" | "4954962" | "5036474" | "5101277" | "5170352" | "5307170" | "5400383" | "5453845" | "5460312").PN.	USPAT	2004/09/22 09:42
-		0	(("4152061" | "4236794" | "4789940" | "4954962" | "5036474" | "5101277" | "5170352" | "5307170" | "5400383" | "5453845" | "5460312").PN.) and (glass near2 pane)	USPAT	2004/09/22 09:47
-		0	(("4152061" | "4236794" | "4789940" | "4954962" | "5036474" | "5101277" | "5170352" | "5307170" | "5400383" | "5453845" | "5460312").PN.) and (influence with glass)	USPAT	2004/09/22 09:48
-		4	("4692806" | "5134473" | "5270756" | "5296926").PN.	USPAT	2004/09/22 09:44
-		0	(("4692806" | "5134473" | "5270756" | "5296926").PN.) and (glass near2 pane)	USPAT	2004/09/22 09:44
-		0	(("4692806" | "5134473" | "5270756" | "5296926").PN.) and (influence with glass)	USPAT	2004/09/22 09:44
-		7	("5068791" | "5247487" | "5949685" | "6047234" | "6226571" | "6275773" | "6292752").PN.	USPAT	2004/09/22 09:47
-		0	(("5068791" | "5247487" | "5949685" | "6047234" | "6226571" | "6275773" | "6292752").PN.) and (glass near2 pane)	USPAT	2004/09/22 09:48
-		0	(("5068791" | "5247487" | "5949685" | "6047234" | "6226571" | "6275773" | "6292752").PN.) and (influence with glass)	USPAT	2004/09/22 09:48

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